



MESH MULTIPLICATION PACKAGE INTO CODE_SATURNE AND ACHIEVED RESULTS

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How to achieve exascale

... -> Peta -> Exa

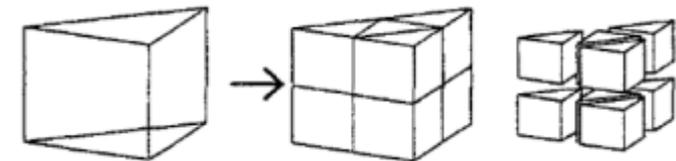
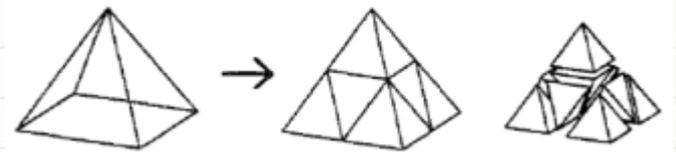
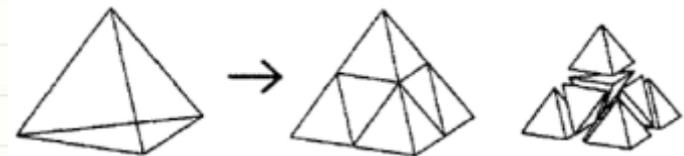
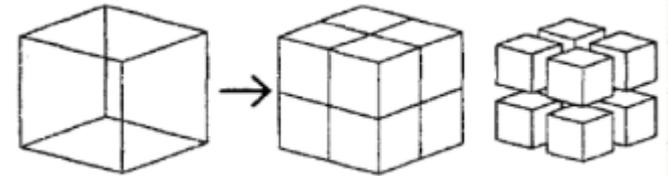
- PRACE, EDF + STFC + IT4I
- Real complex problem
- Fully defined
- Test case: LES in staggered distributed tube bundles
- Architecture
- Solver -> Code_Saturne
- Large mesh (3D) – mesh generators?
- Post-processing
- Visualization

Mesh Multiplication - Overview

- Working with mesh of Billion cells
- Create or load such a mesh is very expensive
- Global refinement
- Existing coarse mesh suitable for CFD simulations, changing size by subdivision of each cell
- Creating very fine mesh, much lesser time of loading and partitioning
- higher accuracy of the solution is attained
- 13 million cell mesh to 6.6 Billion – 10 time steps
- 51 million cell mesh to 26 Billion – 1 time step
- Code_Saturne is able to solve that large problem

Mesh Multiplication - Connectivity

- Several methods of subdivision
- Different behaviour of refinement for hexahedra, tetrahedra, prism or pyramid cells
- Edge midpoints subdivision
- Global connectivity ensured
- Cheap way of indices computation
- No unnecessary core-to-core communication
- Reasonable times of refinement due to the time of whole simulation
- Lot of computational time saved = lot of resources saved for solver



MM and cs_solver.c

- Initialization (global structures)
- Define mesh to read
- Define joining and periodicity
- Set partitioning options
- Read preprocessor output
- **Mesh Multiplication**
- Mesh joining
- Initialize extended connectivity, ghost cells, halo
- Other mesh modifications (geometry, smoothing)
- Save mesh and discard all temporary structures
- Renumbering of a mesh, group classes, quantities, ...
- Main computation
- ...

Mesh Multiplication - Algorithm

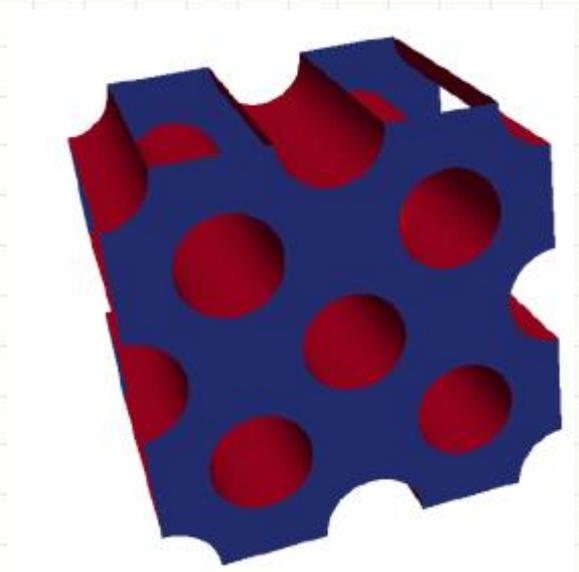
- Input: coarse mesh
- Pre-processing:
 - Create edge local/global numbering,
 - Create faces to edge connectivity,
 - Define cells.
- Refinement:
 - Create new vertices on edges, on border and interior rectangular faces,
 - Refine all faces that inherit family and group from parent.
- Cell refinement:
 - Preparation:
 - Create new vertex in the centre of gravity of the hexahedral cell,
 - Order faces of the cell to ensure positiveness of normal vectors,
 - Prepare indices of vertices.
 - Cell subdivision:
 - Refine the cell,
 - Create new interior faces,
 - Assign proper face to cell connectivity to each new face and cell.
- Output: refined mesh.

Mesh Multiplication - Indexation

- Vertices
 - From coarse mesh keep indices
 - Edge vertex: $n_vertices + edge_idx$
 - Rectangular face vertex: $n_vertices + n_edges + face_idx$
 - Hexa cell vertex: $n_vertices + n_edges + n_faces + cell_idx$
- Faces
 - Every face refined into 4
 - Refined face: $4*(face_idx - 1) + 1:4$
 - New face (cell subdivision): $4*n_faces + T*(cell_idx-1) + 1:T$
 - T – depends on mesh (12 for hexa, tetra, 10 for prism,...)
- Cells
 - New cell: $T*(cell_idx-1) + 1:T$
 - T – depends on mesh (8 for hexa, tetra, prism, ...)

Results

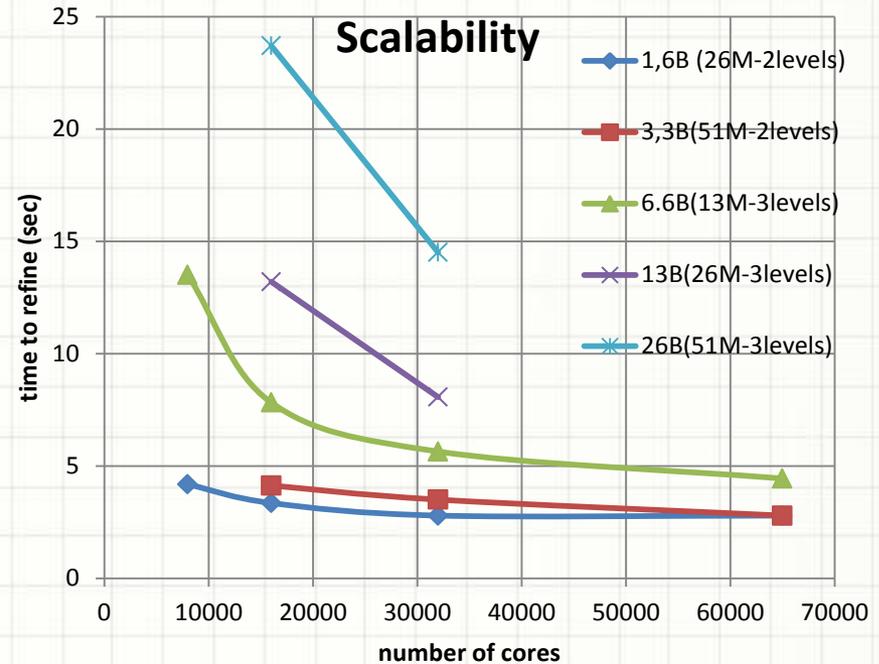
- Different architectures
- Different cases
- Mesh of 51 million cells
- Refined to 26 Billion on 65k cores
- 1 time step C_S – 12288 MPI + 8 OpenMP = ~500s



Parameters of given mesh	Level of MM:		0	1	2	3
	no. of	cells	51M	409M	3.3B	26B
	border faces	1.7M	6.7M	27M	108M	
	interior faces	153M	1.2B	9.8B	78B	
	vertices	52M	413M	3.3B	26B	
Number of cores	16k cores	time [s]	-	2.0(4k)	4.13	23.7
		cells per core	3k	100k	200k	1.6M
	32k cores	time [s]	-	1.89(8k)	3.5	14.5
		cells per core	1.5k	50k	100k	800k
	65k cores	time [s]	-	1.2(16k)	2.79	-
		cells per core	800	25k	50k	400k

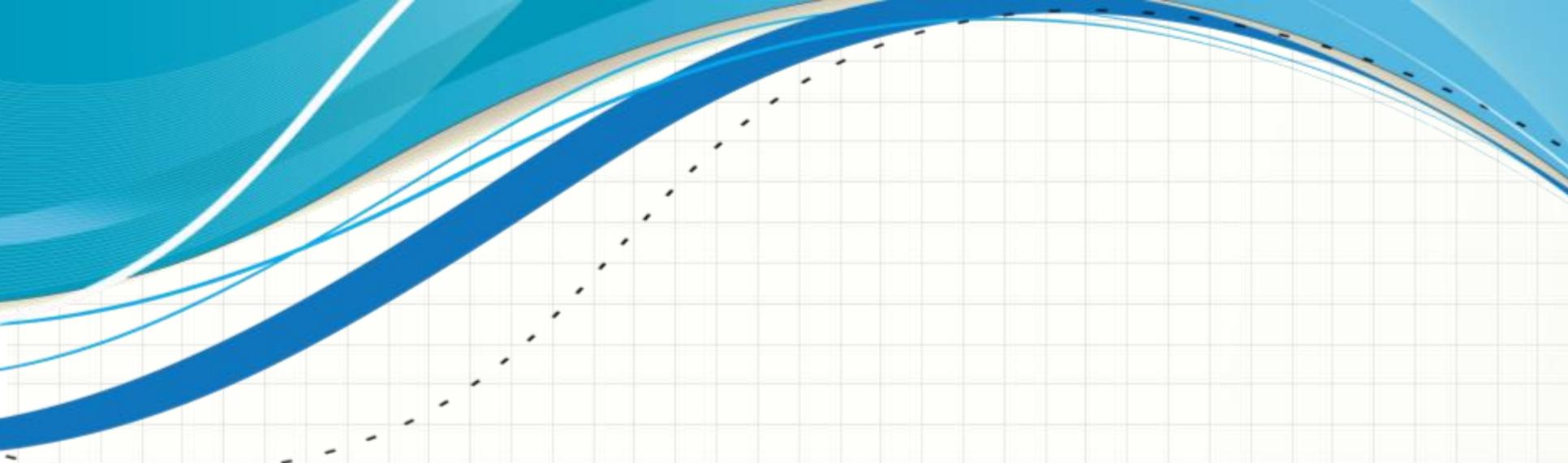
Scalability

- Good scalability up to 65k cores
- MM takes just a fraction of time due to whole computation
- MM of coarser mesh is much cheaper than creating and loading fine mesh



Perspectives

- `cs_user_mesh`
 - Pyramids and prisms – hybrid meshes
 - Option of mesh multiplication for every C_S user (0-default)
- Adaptive refinement
 - Global refinement adaptive to geometry
 - Local refinement based on a priori (geometry,...) and a posteriori (gradient, error, ...) estimates
 - Remeshing, demeshing
 - Floating parts of a mesh, changing size, shape
- Polyhedral meshes
 - Global/ adaptive refinement of general polyhedral mesh



THANK YOU